



POS MV

MAXIMIZE YOUR ROI WITH POS MV OCEANMASTER

POS MV OceanMaster is a user-friendly, turnkey system designed and built to provide accurate attitude, heading, heave, position, and velocity data of your marine vessel and onboard sensors.

POS MV is proven in all conditions, and is the georeferencing and motion compensation solution of choice for the hydrographic professional.

POS MV blends GNSS data with angular rate and acceleration data from an IMU and heading from the GPS Azimuth Measurement System (GAMS) to produce a robust and accurate full six degrees-of-freedom position and orientation solution.

Key Features

- ▶ 0.01° roll and pitch performance
- ▶ IN-Fusion 2.0 ensures optimal GNSS aiding for any given conditions
- ▶ TrueHeave - no requirement to tune filter for specific conditions, no settling time so no run in time
- ▶ High accuracy inertial measurement units featuring SmartCal
- ▶ Data time tagged to microsecond accuracy



CODEVINTEC
Tecnologie per le Scienze della Terra e del Mare

PERFORMANCE SUMMARY

POS MV OCEANMASTER ACCURACY¹

| | DGPS | Fugro Marinestar ⁴ | IARTK | POSPac MMS PPP | POSPac MMS IAPPK | Accuracy Following 60 s GNSS Outage |
|---------------------------|--|---|---|--|--|---|
| Position | 0.5 - 2 m ² | Horizontal: 10 cm 95% Vertical: 15 cm 95% | Horizontal: +/- (8 mm + 1 ppm x baseline length) ³ Vertical: +/- (15 mm + 1 ppm x baseline length) ³ | Horizontal: < 0.1 m Vertical: < 0.2 m | Horizontal: +/- (8 mm + 1 ppm x baseline length) ³ Vertical: +/- (15 mm + 1 ppm x baseline length) ³ | ~ 6 m (DGPS) ~ 3 m (RTK) ~ 2 m (PPDGNSS) ~ 1 m (IAPPK) |
| Roll & Pitch ⁴ | 0.02° | 0.01° | 0.01° | < 0.01° | 0.008° | 0.03° |
| Heading ⁴ | 0.01° with 4 m baseline 0.02° with 2 m baseline | 0.01° with 4 m baseline 0.02° with 2 m baseline | 0.01° with 4 m baseline 0.02° with 2 m baseline | 0.01° with 4 m baseline 0.02° with 2 m baseline | 0.01° with 4 m baseline 0.02° with 2 m baseline | 1° per hour degradation (negligible for outages <60 s) |
| Heave TrueHeave™ | 5 cm or 5% ⁵ 2 cm or 2% ⁶ | -5 cm or 5% ⁵ 2 cm or 2% ⁶ | 5 cm or 5% ⁵ 2 cm or 2% ⁶ | - | - | 5 cm or 5% ⁵ 2 cm or 2% ⁶ |

PCS OPTIONS

| COMPONENT | DIMENSIONS | WEIGHT | TEMPERATURE | HUMIDITY | POWER |
|-----------------------|-----------------------------------|--------|------------------|-------------|--|
| Rack Mount PCS | L = 442 mm, W = 356 mm, H = 46 mm | 3.9 kg | -20 °C to +70 °C | 10 - 80% RH | AC 120/230 V, 50/60 Hz, auto-switching |
| Small Form Factor PCS | L = 167 mm, W = 185 mm, H = 68 mm | 2.5 kg | -20 °C to +60 °C | 0- 100% RH | DC 10-34 V, 35 W (peak) |

INERTIAL MEASUREMENT UNIT (IMU)

| ENCLOSURE | DIMENSIONS | WEIGHT | TEMPERATURE | HUMIDITY | IP RATING |
|---------------|--|--------|------------------|----------|-----------|
| Between Decks | L = 158 mm, W = 158 mm, H = 124 mm | 2.5 kg | -40 °C to +60 °C | | IP65 |
| Submersible | Ø100 mm (base plate Ø132 mm) X 104 mm ⁷ | 2.7 kg | -40 °C to +60 °C | | IP68 |

GLOBAL NAVIGATION SATELLITE SYSTEM (GNSS)

| COMPONENT | DIMENSIONS | WEIGHT | TEMPERATURE | HUMIDITY |
|----------------------|--------------------|---------|------------------|-----------|
| GNSS antenna (540AP) | Ø178 mm, W = 73 mm | 0.45 kg | -50 °C to +70 °C | 0-100% RH |
| GNSS Antenna (GA830) | Ø149 mm, W = 99 mm | 0.82 kg | -40 °C to +70 °C | 0-100% RH |

ETHERNET INPUT/OUTPUT

Ethernet (10/100 base-T)
Parameters Time tag, status, position, attitude, velocity, track and
speed, dynamics, performance metrics, raw IMU data
raw GNSS data
Display Port Low rate (1 Hz) UDP protocol output
Control Port TCP/IP input for system commands
Primary Port Real-time (up to 200 Hz) TCP/IP protocol output
Secondary Port Buffered TCP/IP protocol output for
data logging to external device

SERIAL RS232 INPUT OUTPUT

5 COM Ports User assignable to: NMEA output (0-5),
Binary output (0-5), Auxiliary GNSS input
(0-2), Base GNSS correction input (0-2)

NMEA ASCII OUTPUT

Parameters NMEA Standard ASCII messages: Position (\$INGGA),
Heading (\$INHDT), Track and Speed (\$INVTG), Statistics
(\$INGST) Attitude (\$PASHR, \$PRDID), Time and Date (\$INZDA, \$UTC)
Rate Up to 50 Hz (user selectable)
Configuration Output selections and rate individually
configurable on each assigned com port

HIGH RATE ATTITUDE OUTPUT

Parameter User selectable binary messages: attitude,
heading, speed
Rate Up to 200 Hz (user selectable)
Configuration Output selections and rate individually
configurable on each assigned com port

AUXILIARY GNSS INPUTS

Parameter NMEA Standard ASCII messages: \$GPGGA,
\$GPGST, \$GPGSA, \$GPGSV
Uses Aux input with best quality
Rate 1 Hz

BASE GNSS CORRECTION INPUTS

Parameter RTCM V2.x, RTCM V3.x, CMR, CMR+, and
CMRx input formats accepted. Combined
with raw GNSS observables in navigation solution
Rate 1 Hz

DIGITAL I/O

1PPS 1 pulse-per-second Time Sync output, normally high, active low pulse
Event Input (2) Time mark of external events. TTL pulses >
1 msec width, rising or falling edge, max rate 200 Hz

USER SUPPLIED EQUIPMENT

- PC for POSView Software (Required for configuration): Pentium 90 processor (minimum), 256 MB RAM, 2 GB free disk space, Ethernet adapter (10/100 Base-T Ethernet; IEEE 802.3 standard), Windows 7 SP1, Windows 7 Embedded, Windows 8, and Windows 10
- PC for POSpac MMS Post-processing Software: Intel Pentium series 1Ghz or or faster 64-bit processor (minimum), 2GB RAM, 2.6 GB free disk space, USB Port (For Security Key), Windows 7 SP1, Windows 8.1, Windows 10

¹ Sigma unless otherwise stated

² Depending on quality of differential corrections

³ Assumes 1 m IMU-GNSS antenna offset

⁴ No range limit

⁵ Whichever is greater, for periods of 20 seconds or less

⁶ Whichever is greater, for periods of 35 seconds or less

⁷ Height excludes connector

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